



ISTITUTO ITALIANO
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TITLE

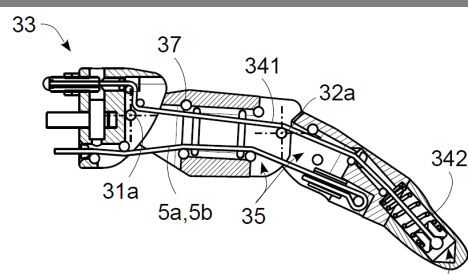
Prosthetic finger

INVENTORS

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DESCRIPTION

The invention is based on a robotic finger adapted to be implemented on a suitably underactuated robotic hand and, in particular, to a prosthetic or myoelectric hand.



APPLICATIONS

Prosthetic

KEYWORDS

Prosthetic finger, cables, pulleys, actuator, compression spring, sliding pins

BIBLIOGRAPHIC DATA

Dito protesico

Application Number IT 102018000005214

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Applicants Fondazione Istituto Italiano di Tecnologia, Istituto nazionale per l'assicurazione contro gli infortuni sul lavoro

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